



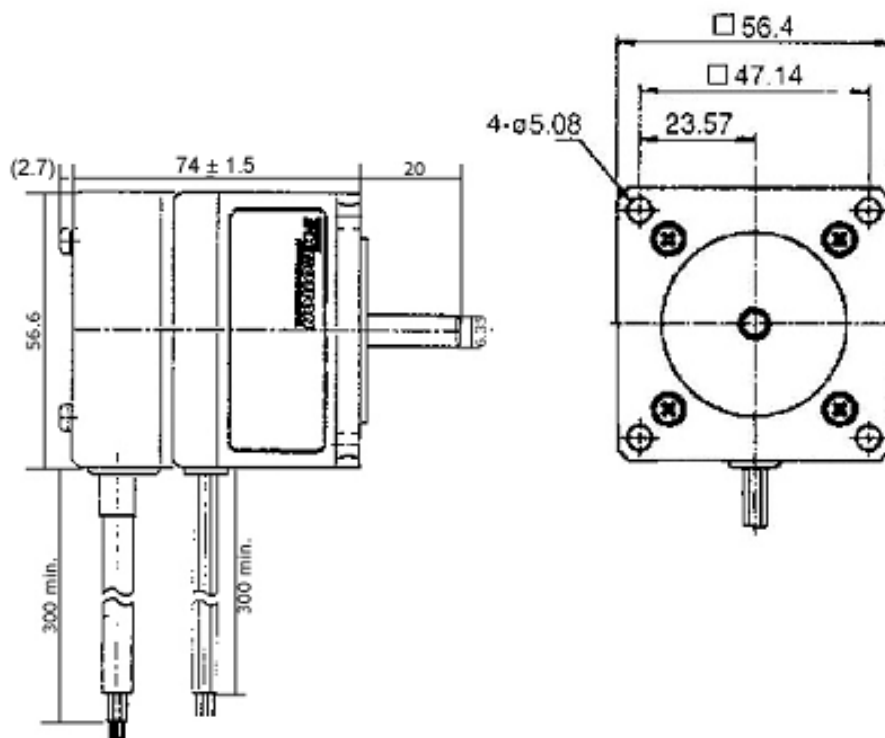
## ECM265 Baureihe

### 2-Phasen-Schrittmotor mit Encoder [1,8° Standard-Version]

Auslaufmodell

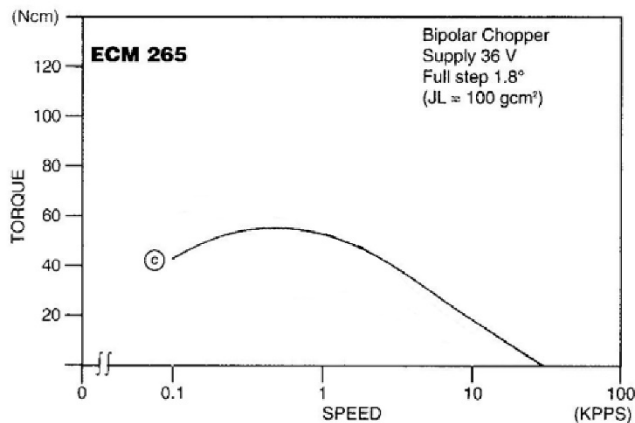
Model	● Bipolar Parallel				● Bipolar Seriell				● Unipolar				Speed Torque
	Holding Torque [Nm]	Current / Phase [A]	Resistance / Phase [Ohm]	Inductance / Phase [mH]	Holding Torque [Nm]	Current / Phase [A]	Resistance / Phase [Ohm]	Inductance / Phase [mH]	Holding Torque [Nm]	Current / Phase [A]	Resistance / Phase [Ohm]	Inductance / Phase [mH]	
ECM265-E2.6P2200	0.6	3.7	0.36	0.9	0.6	1.85	1.44	3.6	0.45	2.6	0.72	0.9	c

Number of Leads	Weight of Motor & Encoder	Size Length	Rotor Inertia
8	0.61 kg	76.7mm	$57 \times 10^{-7} \text{kgm}^2$

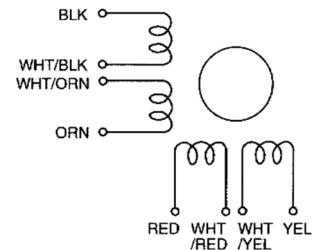


Optional sind für unsere Schrittmotoren Planetengetriebe erhältlich.

# EC MOTION



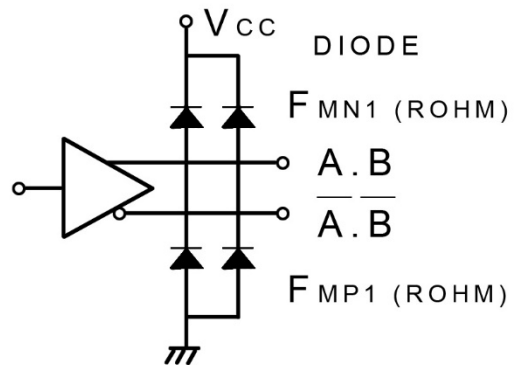
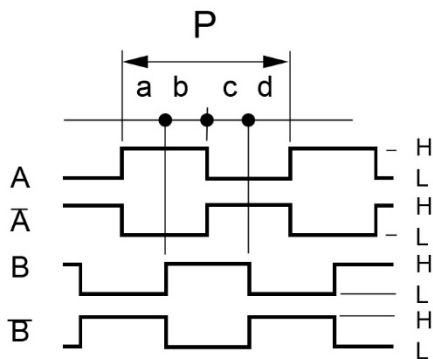
## Schrittmotoranschluss



## Encoder Performance

Operating Temp.range : 0°C – 85°C  
 Supply : DC 5V ± 5% , 100mA max  
 Resolution : 200 Counts / Turn  
 Frequency Response : 100K Hz max.  
 A phase difference : 1/4 P ± 1/8 P  
 Code : Incremental A.B (2Ch.)

Output Signal : when output is high : DC 2.4V min  
 Output Signal : when output is low : DC 0.4V max  
 Sinking & Output Current : typical ± 20mA max  
 Rise & Fall Times : 1 µsec max  
 Moment of inertia : 5 g-cm<sup>2</sup> max Encoder only  
 Output Circuit : Line Driver AM26C3IIDB



CW Rotation viewed from mounting end. Encoder signal A and B position is "H" at Motor 2Phase on.

## Color of Leadwires and Funktion :

DC 5V = red      A phase = brown      A-bar phase = orange  
 GND = blue      B phase = yellow      B-bar phase = gray

(Old-Version)

A phase = brown      A-bar phase = orange  
 B phase = yellow      B-bar phase = white  
 DC 5V = red      GND = black